

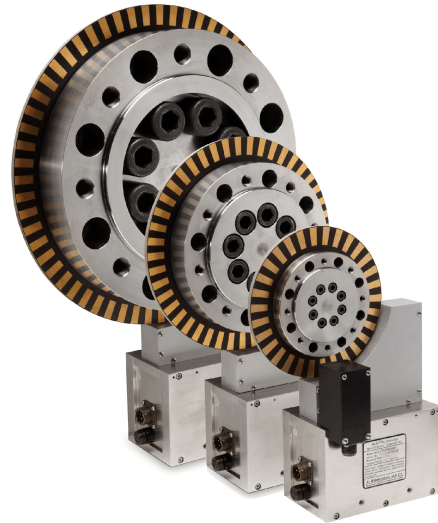
MCRT[®] 84700V Bearingless Dual Range Digital Torquemeters

High Ranges: 500 to 100,000 lbf-in (56.5 Nm to 11,300 Nm); Low Ranges: 100 to 20,000 lbf-in (11.3 to 2,260 Nm)

BEST REAL WORLD ACCURACY OF ANY TORQUEMETER, TORQUE SENSOR OR TORQUE TRANSDUCER

WIDEST INSTALLED MEASUREMENT BANDWIDTH AND FASTEST INSTALLED RESPONSE
SIMPLE TO INSTALL, TOLERANT OF WIDE ROTOR-STATOR MISALIGNMENT
LOWEST SENSITIVITY TO CLAMPING LOADS
HIGHEST OVERRANGE AND OVERLOAD
0.03% COMBINED NONLINEARITY & HYSTERESIS
NOISE TOLERANT CARRIER AMPLIFICATION
BI-DIRECTIONAL ROTOR SHUNT CALIBRATION
NO HOOP OR CALIPER ANTENNAE

- Digital Output of Torque & Temperature
- Analog and FM Outputs
- 3 kHz Signal Bandwidth
- Max/Min's Updated at 20 kHz
- 200% & 1,000% Overload, 300% Overrange
- 0.0003%/°F Compensation
- 0.036% Accuracy Class
- 13 Bessel Data Filters
- Interface Software Furnished



*NIST traceable calibration performed in our accredited laboratory (NVLAP Lab Code 200487-0). For details visit www.himmelstein.com or follow the accreditation link at www.nist.gov.

MCRT[®] 84700V Dual Range Torquemeters *measure high and low torques with high accuracy and without the cost and inconvenience of swapping two conventional sensors.* They correctly measure torque if the peak to average ratio is high. Their use avoids the accuracy loss that occurs if an oversized sensor is used to prevent damage.

Accuracy is high in real-world applications, not just in the cal lab. That's due, in part, to very high stiffness which yields wider installed bandwidth and faster response than competitive¹ device. Industries highest Overrange avoids errors² from clipped torque peaks. Carrier amplification, immune to dc and low frequency ac, handles strain bridge signals. Also enhancing real world performance is noise hardening against EMI from VFD's, ISM transmitters and other noise sources.

1. See Application Note 221101D 2. See Application Note 20805B

Each range is calibrated to full scale with 8 to 9 CW and CCW steps (17 to 20 total) and documented by a NVLAP approved certificate certifying NIST traceability and that our laboratory operation and quality management system meet ISO/IEC 17025:2005. A Bi-directional rotor shunt cal verifies calibration and operation of the entire data chain in **CW and CCW modes**. It is invoked via stator switches, I/O line or from your computer.

Multiple bridges and elegant design provide **exceptional immunity to clamping and other extraneous loads**. The torque signal is digitized on the rotor and sent to the stator where analog, frequency and Com Port outputs are created. Choose RS232/RS422/RS485 or USB communications. Included software interfaces with your Windows-based PC. It displays Real-time, Max/Min and Spread Torque, Rotor Temperature, checks limits, does torque time plots and stores test results.

S. HIMMELSTEIN AND COMPANY

Designing and Making the World's Best Torque Instruments Since 1960

Exceptional Immunity To Noise And Interference From ISM Transmitters

Bearingless Torquemeters use unshielded antennae. As a result, any device (including a like Torquemeter) operating at or near their carrier frequency, can cause interference. FCC rules allow ISM devices to generate unlimited energy. Because most Bearingless Torquemeters use an ISM frequency for data transfer, they are susceptible to interference from other ISM devices.

Since FCC rules only allow narrow band (typically ± 7 kHz) transmission for unlicensed use, wideband ISM frequency Torquemeters risk violation of FCC regulations. Himmelstein Bearingless Torquemeters use non-ISM frequencies for power and data, have field strengths within FCC rules, powerful 12 pole signal filters and near field (not radiated field) signal transfer.

Common Specifications*	High Range	Low Range
Torque Range¹	Factory Set @ Transducer Full Scale Torque; see Note 1.	
Torque Units of Measure	Select lbf-in, lbf-ft, ozf-in, ozf-ft, N-m, kN-m, N-cm, kgf-m, kgf-cm, gf-cm without re-calibration	
Temperature Units of Measure	Select °F or °C without re-calibration	
Combined Nonlinearity & Hysteresis (% of Range, Best Fit Line Basis - see Tech Memo 230104)	$\leq \pm 0.03\%$ of High Range	$\leq \pm 0.05\%$ of Low Range
Overrange² (% of Range)	150	300
Overload (% of Range)	200	1,000
Repeatability	$\leq \pm 0.01\%$ of Range	$\leq \pm 0.015\%$ of Range
Accuracy Class³	$\leq \pm 0.036\%$	$\leq \pm 0.05\%$
Calibration Signal⁴	100.00% of full scale for clockwise and counterclockwise directions.	
Zero Drift (% of Range per °F/per °C)	$\leq \pm 0.0003/0.00054$	$\leq \pm 0.0015/0.0027$
Span Drift (% of Reading per °F/per °C)	$\leq \pm 0.002/0.0036$	$\leq \pm 0.002/0.0036$
48 Hour Drift (% of Range - applies to all outputs)	$\leq \pm 0.01$	$\leq \pm 0.05$
Temperature Ranges (°F/°C)	Compensated Range: +75 to +175/+24 to +79.4; Usable Range: -25 to +185/-32 to +85 Storage Range: -65 to +225/-54 to +107	
Rotor to Stator Maximum Misalignment (inches/mm)	Axial: $\pm 0.4/10.2$, Radial: 0.3/7.6 with or without Optical (Code O) Speed Pickup Option. If Magnetic (Code Z) Speed Pickup Option is installed, then both maximums become 0.04/1.0.	
Effect of Clamping Loads (% of Range)	$\leq \pm 0.02$	$\leq \pm 0.1$
Analog Output Signals⁵, Auto-Scaled	Allowable Load: 10k resistive, minimum; 0.05 μ F capacitive, maximum.	
Full Scale Torque, Both Ranges	$\pm 10V$ with $\pm 15V$ overrange. User may select $\pm 5V$ with $\pm 7.5V$ overrange. Caution: see Note 2. $\pm 5V$ with $\pm 15V$ overrange. User may select $\pm 10V$ with $\pm 15V$ overrange. Caution: see Note 2.	
Signal Filter Cutoff Frequency⁶	From 0.1 Hz to 1 kHz in thirteen 1-2-5 steps plus 3 kHz. Selected from a remote PC using furnished software.	
Frequency Modulated Output⁵	Frequency: $10 \pm 5/20 \pm 10/40 \pm 20$ kHz; field changeable (Default = 10 ± 5 kHz); TTL square wave output.	
Peak-Peak Digital Output⁵ Noise vs Filter Cutoff Frequency (% of Range)	0.0002 @ 0.1Hz and 1 Hz, 0.004 @ 10 Hz, 0.011 @ 100 Hz, 0.04 @ 1 kHz, 0.06 @ 3 kHz	0.001 @ 0.1Hz and 1 Hz, 0.02 @ 10 Hz, 0.05 @ 100 Hz, 0.2 @ 1 kHz, 0.3 @ 3 kHz
Peak-Peak Analog Output^{5,7} Noise on 10V Range vs Filter Cutoff Frequency (millivolt)	4 @ 0.1 Hz thru 10 Hz, 5 @ 100 Hz thru 1 kHz, 6 @ 3 kHz.	4 @ 0.1 Hz thru 10 Hz, 8 @ 100 Hz, 17 @ 1 kHz, 28 @ 3 kHz
Torque Sampling Rate and Bandwidth	20 kHz. 3 dB bandwidth is 3 kHz reducible by filters (see Note 6 & above).	
Rotor-to-Stator Transfer Rate	1.25 MBaud	
RS232/RS422/RS485/USB Communication⁸	Outputs Torque and Temperature with units of measure. Inputs torque range if other than sensor full scale, selects units of measure, selects filter cutoff, etc. and permits remote test control.	
BAUD Rate	115,200; Drivers are protected for short circuit (current limit) and ± 15 kV ESD protected.	
Maximum Cable Length	RS232 = 50 feet, RS422/485 = 4,000 feet; 120 Ohm termination may be accessed via software.	
Interface Software With Torque Limits	Provided to interface with Windows-based PC. Includes 20 foot interconnect cable for a PC.	
I/O Lines and FM Output⁵	Input lines are +CAL, -CAL, TARE, CLEAR TARE, and TOGGLE RANGE. Output lines are Data OK & FM Out.	
Status LED's (on Stator Keypad)	3 LED's: Power (Yellow = Power-up, Green = OK, Red = Fault); Data (Green = OK, Red = Data Error); Rotor Temperature (Green = In Operating Range, Red = Out of Operating Range).	
Keypad Control Switches	+ CAL invokes CW Rotor Shunt Cal, -CAL invokes CCW Rotor Shunt Cal, Both held simultaneously for 5 seconds invokes TARE.	
Rotor Temperature	Rotor temperature is output via Com Port. Range is 0 to 185 °F.; Accuracy is ± 2 °F.	
Optional Zero Velocity Speed Pickups	Optical and Magnetic pickups output pulse train. Magnetic type restricts misalignment; see above.	
Supply Voltage/Power⁹	10 to 26 VDC @ 6 to 11 Watts nominal, varies with rotor misalignment.	

Specification Notes:

1. Outputs may be set at any value equal to or less than the Torquemeter Full Scale Rating. *For example:* If the Full Scale Rating is 10,000 lbf-in, the user may re-scale to 5,000 lbf-in. Then the analog output would be 5 or 10 Volts at 5,000 lbf-in and the digital output, at the Com Port, would be 5,000. However, the above specification still defines measurement accuracy. In other words, you can use this capability to change the scaling but it will not change measurement accuracy; see Application Note 20804 for further details on Torquemeters operated with extended measuring range.
 2. **In the overrange region** all outputs are guaranteed to have combined nonlinearity and hysteresis lower than 0.1% of full scale. This avoids large average and peak torque errors that driveline resonance and pulsating driver and load devices can cause near the high end of the sensor range. See Application Note 20805B for more complete information. Torquemeters have infinite fatigue life for full reversals up to half their overload rating. Above that, you risk a fatigue failure.

If you are using the analog output, it is linear up to 15 volts. That corresponds to 150% of full scale on the 10 volt output setting and 300% on the 5 volt output setting. Accordingly, when using the analog output and if you expect torque peaks greater than 150% of full scale, you should switch to the 5 volt setting.
 3. The greatest of Combined Error, Repeatability, Zero Drift and Span Drift over 18 °F (10 °C). It is expressed as a percent of full scale..
 4. CW torque causes CW rotation if viewed from the driving end. CCW torque causes the opposite rotation.
 5. Power input and all outputs are protected. Digital inputs are reverse polarity and over-voltage protected.
 6. Torque signal bandwidth upper limit is 3 kHz determined by the integral anti-aliasing filter. Realizable, installed measurement bandwidth is limited by driveline components. A torquemeters principle contribution is determined by its torsional stiffness; see Application Note 221101D for further information.
 7. Analog noise is measured by an Agilent U1520A Scope with bandwidth set to 10 kHz.
 8. A 20 foot long Torquemeter to RS422/485 PC port cable is shipped with each Torquemeter. That communication protocol provides for long, robust connection in a noisy industrial environment, and permits connection of multiple Torquemeters to a single, host computer. An optional USB to RS422/485 adapter is available (P/N 330-0003) if your PC has only USB ports.


Should you prefer to use the RS232 interface and you computer has an integral RS232 port, you can order a Torquemeter to PC cable, P/N 224-8359-20 is a 20 foot cable, P/N 224-8359-50 is a 50 foot cable. If your PC does not have an integral RS232 port, then you should use the RS422/485 interface per above because it provides superior noise immunity due, in part, to the symmetrical signal format, balanced cabling, etc.
 9. Fused and reverse polarity protected.
- * Specifications are subject to change without notice.

ORDER NUMBER FORMAT **MCRT® 84700V A B C**

A = Range from tables above; (2-4) or (5-4), etc.

B = Optional Zero Velocity Speed Pickup; N for None, Z for Magnetic Type, O for Optical Type.

C = Speed Rating Suffix; H designates high speed rating, B designates lower speed rating

ORDER NUMBER EXAMPLE  **MCRT® 84707V(1-5)OH** specifies a Dual Range Bearingless Torquemeter with a 100,000 lbf-in High Range Rating, a 20,000 lbf-in Low Range Rating, a 200,000 lbf-in Torque Overload rating, an Optical Speed Pickup and a 10,000 rpm Maximum Speed Rating.

MCRT® 84700V Dual Range Bearingless Digital Torquemeters

MCRT® Model	High Range			Low Range			Both Ranges
	Full Scale Torque		Maximum Deflection	Full Scale Torque		Maximum Deflection	Maximum Speed
	[lbf-in]	(N-m)	[degree]	[lbf-in]	(N-m)	(degree)	[rpm]
84702V(5-2)	500	56.5	0.054	100	11.3	0.011	15,000 Suffix H or 8,500 Suffix B
84702V(1-3)	1,000	113	0.039	200	22.6	0.008	
84702V(2-3)	2,000	226	0.028	400	45.2	0.006	
84704V(5-3)	5,000	565	0.063	1,000	113	0.012	13,500 Suffix H or 8,000 Suffix B
84704V(1-4)	10,000	1,130	0.045	2,000	226	0.009	
84704V(2-4)	20,000	2,260	0.034	4,000	452	0.007	
84707V(5-4)	50,000	5,650	0.051	10,000	1,130	0.002	10,000 Suffix H or 6,000 Suffix B
84707V(1-5)	100,000	11,300	0.039	20,000	2,260	0.002	

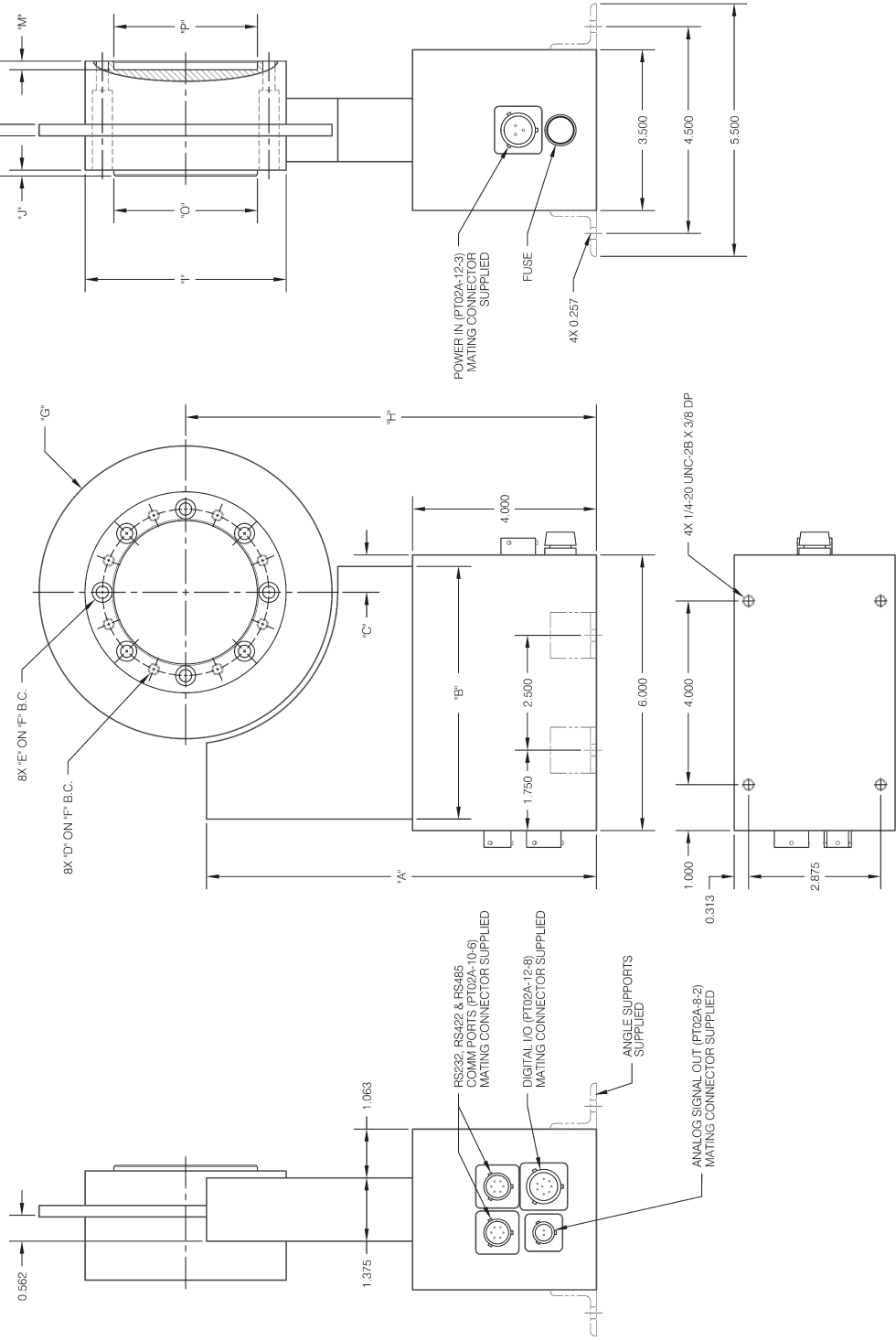
MCRT® Model	All Models (Torque Overload is 200% of the High Range Torque Rating)					Maximum Rotor Weight
	Torsional Stiffness	Rotating Inertia	Maximum Thrust*	Maximum Bending*	Maximum Shar*	
English Units	[lbf-in/rad]	[ozf-in s ²]	[lbf]	[lbf-in]	[lbf]	[lb]
84702V(5-2)	528,000	0.634	500	250	125	5.0
84702V(1-3)	1,480,000	0.635	1,000	500	250	5.0
84702V(2-3)	4,020,000	0.638	2,000	1,000	500	5.0
84704V(5-3)	4,560,000	3.96	3,000	1,500	800	13.3
84704V(1-4)	12,600,000	3.97	4,000	2,000	1,000	13.4
84704V(2-4)	33,900,000	3.99	6,000	3,000	2,000	13.5
84707V(5-4)	55,900,000	29.3	15,000	7,500	4,000	43.3
84707V(1-5)	145,000,000	29.7	25,000	12,500	5,000	44.1
SI Units	[N-m/rad]	[kg-m ²]	[N]	[N-m]	[N]	[kg]
84702V(5-2)	59,650	0.00448	2,220	28.2	556	2.3
84702V(1-3)	167,000	0.00448	4,450	56.5	1,110	2.3
84702V(2-3)	454,000	0.00451	8,900	113	2,220	2.3
84704V(5-3)	515,000	0.0280	13,300	169	3,560	6.0
84704V(1-4)	1,424,000	0.0280	17,800	226	4,450	6.1
84704V(2-4)	3,830,000	0.0280	26,700	339	8,900	6.1
84707V(5-4)	6,316,000	0.207	66,700	847	17,800	19.6
84707V(1-5)	16,382,000	0.210	111,000	1,410	22,200	20.0

* Maximum extraneous loads and rated torque may be applied simultaneously without damage

Dimensions in English Units

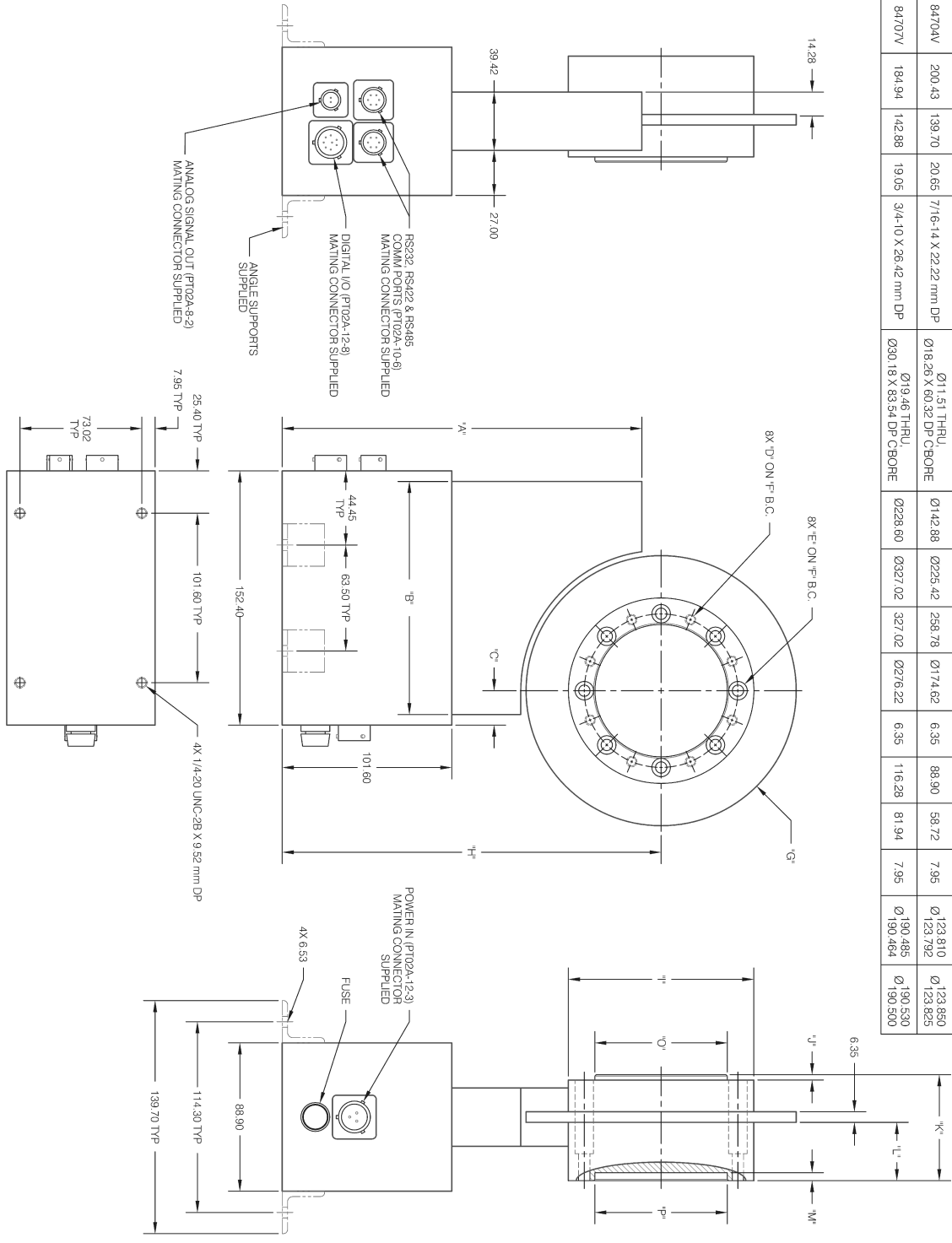
Please note, dimensions subject to change without notice. Contact factory for certified drawings.

MCRT	"A"	"B"	"C"	"D"	"E"	"F"	"G"	"H"	"I"	"J"	"K"	"L"	"M"	"O"	"P"
84702V	8.484	5.500	0.813	1/4-20 X 1/2 DP	Ø0.266 THRU, Ø0.438 X 1.738 DP C-BORE	Ø3.625	Ø6.375	8.938	Ø4.375	0.125	2.500	1.375	0.188	3.1246 Ø 3.1250	3.1257 Ø 3.1250
84704V	7.891	5.500	0.813	7/16-14 X 7/8 DP	Ø0.453 THRU, Ø0.719 X 2.375 DP C-BORE	Ø5.625	Ø8.875	10.188	Ø6.875	0.250	3.500	2.313	0.313	4.8744 Ø 4.8737	4.8760 Ø 4.8750
84707V	7.251	5.625	0.750	3/4-10 X 1-1/32 DP	Ø0.766 THRU, Ø1.188 X 3.289 DP C-BORE	Ø9.000	Ø12.875	12.188	Ø10.875	0.250	4.578	3.226	0.313	7.4994 Ø 7.4986	7.5012 Ø 7.5000



Dimensions in SI Units

Please note, dimensions subject to change without notice. Contact factory for certified drawings.



MOBT	'A'	'B'	'C'	'D'	'E'	'F'	'G'	'H'	'I'	'J'	'K'	'L'	'M'	'O'	'P'
84702V	215.49	139.70	20.65	1/4-20 X 12.70 mm DP	Ø6.76 THRU Ø11.13 X 44.15 DP C/BORE	Ø92.08	Ø161.92	227.03	Ø111.12	3.18	63.50	34.92	4.78	Ø 79.365	Ø 79.393
84704V	200.43	139.70	20.65	7/16-14 X 22.22 mm DP	Ø11.51 THRU Ø18.26 X 63.32 DP C/BORE	Ø142.88	Ø225.42	258.78	Ø174.62	6.35	88.90	58.72	7.95	Ø 123.810	Ø 123.850
84707V	184.94	142.88	19.05	3/4-10 X 26.42 mm DP	Ø19.46 THRU Ø30.18 X 83.54 DP C/BORE	Ø228.60	Ø327.02	327.02	Ø276.22	6.35	116.28	81.94	7.95	Ø 190.485	Ø 190.530

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